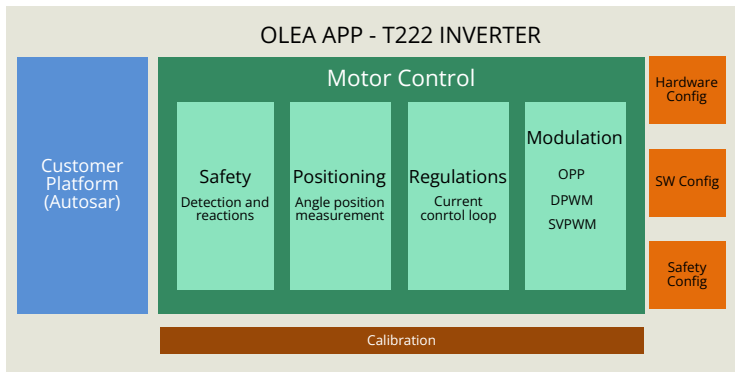
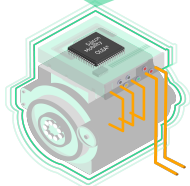


## OLEA<sup>®</sup> APP - T222 INVERTER

Motor control software application for OLEA FPCU delivering unmatched efficiency & performance



- Supports any type of electric motor and position sensors
- Fast control loop and advanced modulation technics (OPP)
- Safety, Control, Configuration and Calibration API
- Safety Interface: Gate drivers and system I/O I/F
- Functional I/O, EPIOs, PWMs and ADC channels
- Gate drivers interface: 3 or 6 phases
- Default and custom safety fault detection and reaction
- ISO26262 ASIL-D Certified



## Complete e-motor control application

The OLEA APP - T222 INVERTER platform is an **embedded software designed for the OLEA T222 FPCU** parallel architecture, enabling high-performance, real-time control of inverter and electric motors. It offers efficient and safe control of torque, speed, current, and rotor using cutting-edge algorithms. This versatile software **suits a wide range of powertrain system** supports the latest technology inverters, and leverages parallel hardware for fast control loops. It also includes a **separate functional safety stack** and supports a model-based design flow for seamless integration.



Adv. Performances



ASIL-D Certified



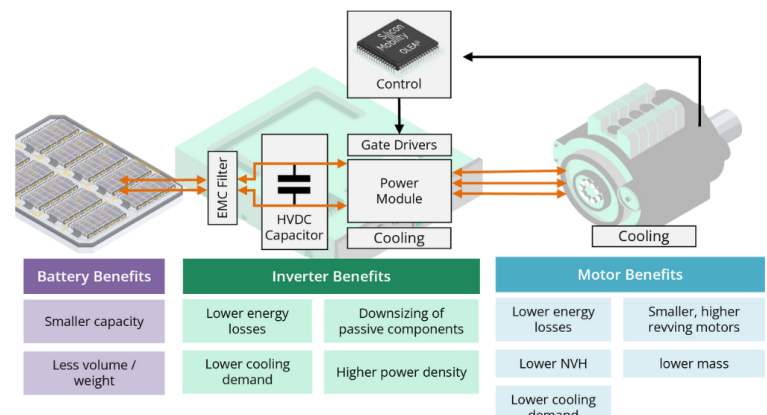
Fast time to market



Flexible & Modular

## Less weight, noise & cost

- Higher control loop and switching frequencies (up to 100 kHz) with optimized Dead Time Compensation
- Short Circuit Withstand Time guarantee at < 300ns
- Advanced modulations (SVPWM, DPWM, 6-step PWM, OPP)
- Improve Total Harmonics Distortion (THD)
- Reduce HVDC Link Voltage Ripple
- High speed machine support (upto 10 kHz electrical frequency)



Vehicle benefits: less weight & cost

# A proven technology

\*These results are derived from actual bench measurements. For the complete document, kindly reach out to our support team.



**Up to 25%**  
E-motor downsizing\*



**Up to 5%**  
Total efficiency improvement\*



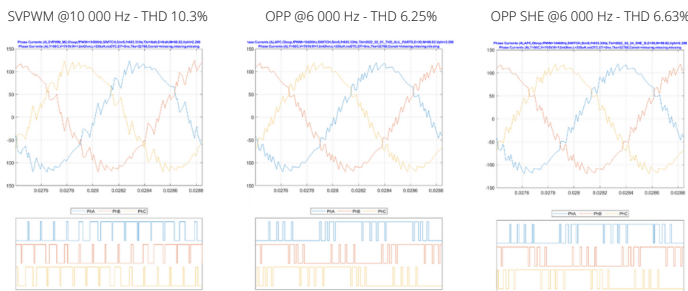
**Up to 53%**  
Cooling downsizing\*



**Reduced by 30%**  
DC-Link Capacitor & EMC\*

## With Optimized Pulse Pattern

Less switching = better efficiency & NVH



Reduce losses, increase efficiency

OPP is part of the **Model-Based driven Predictive Control method** that enables the delivery of unprecedented system performance in terms of energy efficiency, NVH, HVDC ripple, and more. Unlike SVPWM which is time-based, OPP has a **variable number of switches** that can be freely placed on any angular position of the motor.

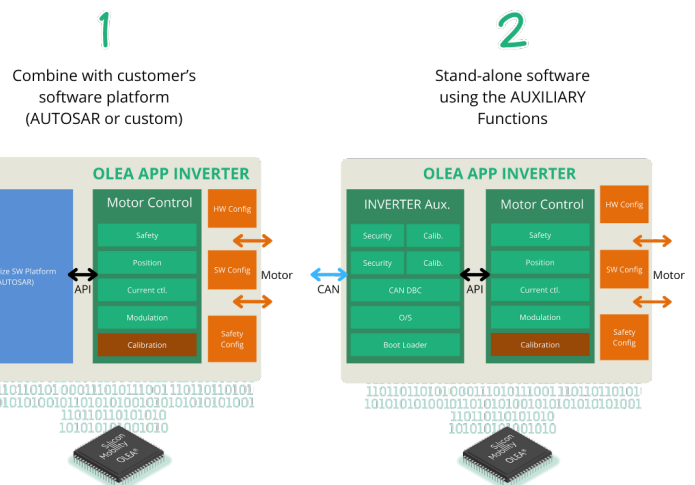
OPP are generated for a defined set of operating points (speed/torque) using an **OPP Generator / Solver** delivered by Silicon Mobility. This tool uses motor loss models to find the OPPs suited for a targeted system

The generated OPPs are used online, in the OLEA APP - T222 INVERTER control software, depending on the operating points. Silicon Mobility goes even further by **offering the possibility to apply the right modulation (between SVPWM, DPWM and OPP) upon the torque/speed need.** This is the Adaptive PWM switching mechanism or APC.

## With Auxiliary Function

The OLEA APP - T222 INVERTER software can be used in two ways: either **combined with a software platform (AUTOSAR or custom)** within the OLEA T222 FPCU, or as a **stand-alone software** in the OLEA T222 FPCU using the Auxiliary Function component. The Auxiliary Function is a recent feature of the OLEA APP - T222 INVERTER platform that allows customers to **preserve their existing software platform in a remote MCU.**

The Auxiliary Function reduces the integration effort when keeping a legacy software platform while benefiting from OLEA performance boost.



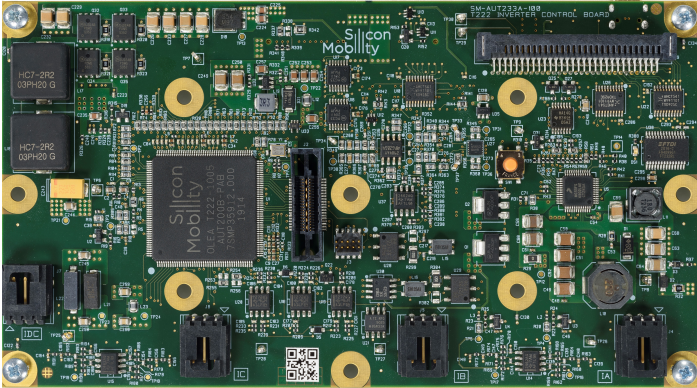
## ASIL-D certified

OLEA APP - T222 INVERTER is **ISO 26262 certified ASIL-D** applications combined with OLEA T222 FPCU. Our solution includes essential documentation and safety work products for integration into tracking inverter application.

# Get your own Starter Kit

For more information about our solutions, visit our website

OLEA COMPOSER – T222 HVIC Starter Kit is based on a reference design board for inverter/electric motor control to enable OLEA technology evaluation, proof of concept, and rapid prototyping.



## The Starter Kit includes:

- OLEA COMPOSER HVIC Control Board with OLEA T222 FPCU & OLEA APP - T222 INVERTER
- Functional Vehicle Dependent Software demo code includes:
  - Remote Control Unit, XCP interface via CAN-FD
  - Diagnostics Interface
- Post-build Measurement, configuration, calibration, and firmware update GUI software for PC Windows
- Schematics, BoM, and User's guide for a fast configuration and calibration

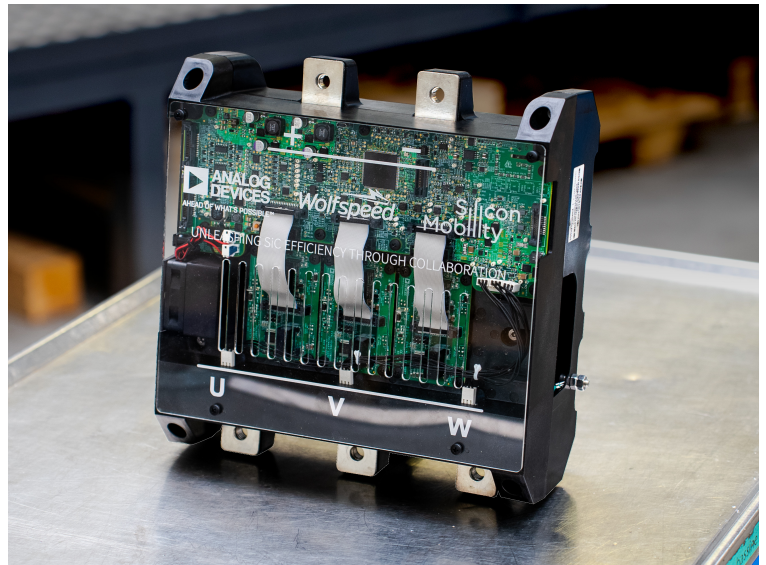
Alternatively, begin with our partnered solution

## 300 kW SiC inverter platform

Best-in-class system-level power density and efficiency obtained by combining ADI's gate drivers, power, isolation, and signal chain solutions with Wolfspeed's efficient SiC MOSFET technology all controlled with Silicon Mobility's software & chip.

### Features:

- 800VDC bus nominal (900V max)
- 360ARMS output
- 80kHz maximum control and switching frequency
- Controller board with OLEA T222 FPCU & OLEA APP - T222 INVERTER
- Supports both SVPWM and DPWM (OPP on request)
- ISO 26262 ASIL-D Certified
- More on the website



## SIC INVERTER Reference Design

This reference design partnered with CISSOID offers the best of both worlds: fast prototyping and adaptable to the application requirements.

### Features:

- 1200V SiC-based power module
- Up to 350kW/850V operation
- Integrated Gate Driver board
- Control board with ultra-fast OLEA T222 FPCU
- Supports both SVPWM and DPWM
- ISO26262 ASIL-D ready
- More on the website



# Fully Featured

## Type of e-motor

- PMSM (Permanent Magnet Synchronous Motor)
- WRSM (Wound Rotor Synchronous Motor)
- ASYM (Asynchronous motor)
- Configurable number of pole pairs
- Uniform air gap (Non-Salient pole machine): when d/q inductances are the same ( $L_d=L_q$ )
- Non uniform air gap (Salient pole machine): when d/q inductances are different ( $L_d \neq L_q$ )
- AFM (Axial Flux Machine)
- RFM (Radial Flux Machine)
- 3 Phases Motor with star connection
- 6 Phases Motor controlled as two-3 phases star connection motors

## Modulation

- SVPWM (Space Vector Pulse Width Modulation)
- DPWM (Discontinuous Pulse Width Modulation)
- OPP (Optimized Pulse Pattern)
- Variable switching frequency based on the electrical speed
- Dead-time compensation

## Motor sensors signal processing

- Position Tracking Loop algorithm for SIN/COS signals with a configurable number of e-motor/resolver configurable pole pairs number
- Position Sensor phase auto calibration at boot
- Position delta phase LUT calibration update at high speed
- Position Gain and Offset auto adjustment of SIN/COS ADC
- AMR-GMR
- Sensorless

## VCU interface

- E-motor Control FSM supporting the VCU operating states
- Fully features set of APIs (control, diagnostics, safety, calibration/ configuration) allowing integration with a VCU

## Auxiliary functions

- CAN Messaging Compliance with CAN DBC
- Pre-emptive O/S Execution
- Real-time Safety Monitoring
- EVITA Light Implementation enables secure firmware updates with storage
- API Access through CAN DBC
- Packaged Auxiliary Software Modules

## E-motor control

- Flux Weakening management
- Active Discharge
- FOC (Field Oriented Control) inc:
- Clarke/Park and Inverse Clarke/park transforms
- D/Q currents filtering using a MAF (Moving Aver. Filter)
- PID coefficient computing with Lambda and bandwidth LUT
- D/Q voltages decoupling
- D/Q voltages saturation
- D/Q inductances LUT
- Fct. of D/Q currents for PMSM
- Fct. of D/Q currents & rotor excitation current for WRSM
- Torque derating LUT based on Speed/DC-Link and  $T^\circ$
- Slew rate limitation: D/Q Currents, switching frequency and rotor DC excitation current (WRSM)
- Filtering of DC Voltage, motor speed, measured  $T^\circ$  and rotor DC excitation current (WRSM)
- $T^\circ$  monitoring: filtered and interpolated using 8 post-build configurable LUT
- Torque control:
- LUT of D/Q Currents based on speed and torque (PMSM)
- LUT of D/Q Currents and LUT of rotor excitation current based on speed and torque (WRSM)
- Current control
- Speed control
- Rotor control
- Enabled automatically for WRSM
- Rotor current regulator parameters computing
- Clockwise/Anti-clockwise direction support

## Safety & diagnostics

- ISO 26262 ASIL-D Ready Design
- Safety Finite State Machine (FSM) managing the faults containment
- Configurable safety faults detections
- Warning detections: Over/under temperature warning